

# 東邦大学学術リポジトリ

Toho University Academic Repository

タイトル	Approximation theorems to a solution to an equilibrium problem in complete geodesic spaces
作成者（著者）	大口, 智輝
公開者	東邦大学
発行日	2024.03
掲載情報	東邦大学大学院理学研究科修士論文令和5年度.
資料種別	学位論文
内容記述	学位取得年月: 2024年3月 / 指導教員: 木村泰紀
著者版フラグ	author
メタデータのURL	<a href="https://mylibrary.toho u.ac.jp/webopac/TD28224453">https://mylibrary.toho u.ac.jp/webopac/TD28224453</a>

Approximation theorems to a solution to an  
equilibrium problem in complete geodesic spaces

6522004 Tomoki Oguchi  
Department of Information Science  
Toho University

Master Thesis  
March 2024

# Contents

Chapter 1	Introduction	2
Chapter 2	Preliminaries	4
2.1	CAT(1) spaces . . . . .	4
2.2	Properties of mappings . . . . .	4
2.3	$\Delta$ -convergence . . . . .	5
2.4	Resolvent of equilibrium problem . . . . .	5
Chapter 3	$\Delta$ -convergence theorem for Mann iteration	7
Chapter 4	$\Delta$ -convergence theorem for projection method	11
Chapter 5	Conclusion	15
	Bibliography	18

# Chapter 1

## Introduction

Let  $X$  be a nonempty set and  $f: K \times K \rightarrow \mathbb{R}$  a function. The problem of finding a point  $x_0 \in K$  such that  $f(x_0, y) \geq 0$  for all  $y \in K$  is called an equilibrium problem. An equilibrium problem includes some important nonlinear problems such as fixed point problems, convex minimization problems, and variational inequality problems. An equilibrium problem was first studied by Blum and Oettli [1] on a Banach space. They introduced a mapping called resolvent of bifunction for an equilibrium problem. The resolvent is an important mapping that allows the equilibrium problem to be reduce to the fixed point problem. Later, Combettes and Hirstoaga introduced the resolvent in a Hilbert space, and showed many important properies of the resolvent.

**Theorem 1.1** (Combettes–Hirstoaga [2]). *Let  $H$  be a Hilbert space, and  $K$  a nonempty, closed convex subset of  $H$ . Suppose that  $f: K \times K \rightarrow \mathbb{R}$  satisfies the conditions (E1)–(E4).*

- (E1)  $f(x, x) = 0$  for all  $x \in K$ ;
- (E2)  $f(x, y) + f(y, x) \leq 0$  for all  $x, y \in K$ ;
- (E3)  $f(x, \cdot): K \rightarrow \mathbb{R}$  is lower semicontinuous and convex for all  $x \in K$ ;
- (E4)  $f(\cdot, y): K \rightarrow \mathbb{R}$  is upper hemicontinuous for all  $y \in K$ .

Define the resolvent  $J_f$  by

$$J_f x = \left\{ z \in K \mid \inf_{y \in K} (f(z, y) + \langle z - x, y - z \rangle) \geq 0 \right\}$$

for  $x \in H$ . Then  $J_f$  has the following properties:

1. The domain of  $J_f$  is  $H$ ;
2.  $J_f$  is single-valued and firmly nonexpansive;
3. the set of all fixed points of  $J_f$  coincides with  $\text{Equil } f$  and it is closed and convex.

Further, the resolvent was generalized to the setting of CAT(0) space and CAT(1) spaces.

On the other hand, a fixed point problem is an example of an equilibrium problem, and Mann type method is a famous technique.

The following result is deduced from Reich's result [9] which was proved in the

setting of uniformly convex Banach spaces.

**Theorem 1.2.** *Let  $H$  be a Hilbert space and let  $C$  be a nonempty closed convex subset of  $H$ . Let  $T$  be a nonexpansive mapping of  $C$  into itself such that  $F(T) \neq \emptyset$ . Assume that  $\{\alpha_n\} \subset [0, 1]$  satisfies  $0 \leq \alpha_n < 1$  and  $\sum_{n=1}^{\infty} \alpha_n(1 - \alpha_n) = \infty$ . Let  $\{x_n\}$  be a sequence of  $C$  defined by  $x_1 = x \in C$ , and*

$$x_{n+1} = \alpha_n x_n + (1 - \alpha_n) T x_n$$

*Then  $\{x_n\}$  converges weakly to an element  $z \in F(T)$ .*

In this thesis we obtain convergence theorems of an iterative sequence to a solution of equilibrium problem on CAT(1) spaces by using the technique of approximation theorems of solution to a fixed point problem.

# Chapter 2

## Preliminaries

In this chapter, we define a CAT(1) space and introduce several important notions for the main results.

### 2.1 CAT(1) spaces

Let  $X$  be a metric space. For  $x, y \in X$ , a mapping  $c : [0, d(x, y)] \rightarrow X$  is called a geodesic if  $c(0) = x, c(d(x, y)) = y$ , and  $d(c(u), c(v)) = |u - v|$  for any  $u, v \in [0, d(x, y)]$ . An image  $[x, y]$  of  $c$  is called a geodesic segment joining  $x$  and  $y$ .  $X$  is called a uniquely  $\pi$ -geodesic space if for every  $x, y \in X$  satisfying  $d(x, y) < \pi$ , there exists a unique geodesic  $c$ . In a uniquely  $\pi$ -geodesic space  $X$ , for all  $x, y \in X$  with  $d(x, y) < \pi$  and  $t \in [0, 1]$ , there exists a unique point  $z \in [x, y]$  such that  $d(x, z) = (1 - t)d(x, y)$ , and  $d(z, y) = td(x, y)$ . We denote it by  $tx \oplus (1 - t)y$ . For  $x, y, z \in X$ , we define a geodesic triangle  $\Delta(x, y, z)$  as the union of three segments  $[x, y]$ ,  $[y, z]$ , and  $[z, x]$ . For a geodesic triangle  $\Delta(x, y, z)$  with  $d(x, y) + d(y, z) + d(z, x) < 2\pi$ , its comparison triangle  $\Delta(\bar{x}, \bar{y}, \bar{z})$  in two dimensional unit sphere  $\mathbb{S}^2$  is a triangle such that each corresponding edge has the same length as that of original triangle. A point  $\bar{p} \in [\bar{x}, \bar{y}]$  is called a comparison point of  $p \in [x, y]$  if  $d(x, p) = d(\bar{x}, \bar{p})$ .  $X$  is called a CAT(1) space if for any  $p, q \in \Delta(x, y, z)$  and their comparison point  $\bar{p}, \bar{q} \in \Delta(\bar{x}, \bar{y}, \bar{z})$ , the inequality

$$d(p, q) \leq d(\bar{p}, \bar{q})$$

holds for any triangle in  $X$ . We say  $X$  is admissible if for all  $x, y \in X$ ,  $d(x, y) < \pi/2$

In CAT(1) spaces, the following inequality holds;

$$\cos d(tx \oplus (1 - t)y, z) \sin d(x, y) \geq \cos d(x, z) \sin td(x, y) + \cos d(y, z) \sin(1 - t)d(x, y)$$

for each  $x, y, z \in X$  and  $t \in [0, 1]$ .

### 2.2 Properties of mappings

Let  $X$  be a CAT(1) space and let  $T : X \rightarrow X$  be a mapping. We call  $x \in X$  a fixed point of  $T$  if  $x = Tx$ , and denote the set of all fixed point of  $T$  by  $F(T)$ . The closed

convex hull  $\text{clco } C$  of subset  $C$  of  $X$  is defined as the intersection of all closed convex subsets of  $X$  including  $C$ .  $X$  has the convex full finite property if every continuous mapping  $T: \text{clco } E \rightarrow \text{clco } E$  has a fixed point for every finite subset  $E$  of  $X$ . A mapping  $T: X \rightarrow X$  is said to be

- nonexpansive if

$$d(x, y) \geq d(Tx, Ty)$$

for  $x, y \in X$ ;

- quasinonexpansive if

$$d(x, u) \geq d(Tx, u)$$

for  $x \in X$  and  $u \in F(T) \neq \emptyset$ ;

- spherically nonspreading of sum type if

$$2 \cos d(Tx, Ty) \geq \cos d(x, Ty) + \cos d(Tx, y);$$

for  $x, y \in X$ .

## 2.3 $\Delta$ -convergence

Let  $X$  be CAT(1) space and  $\{x_n\} \subset X$  a sequence. An asymptotic center  $\text{AC}(\{x_n\})$  of  $\{x_n\}$  is defined by

$$\text{AC}(\{x_n\}) = \left\{ z \in X \mid \inf_{x \in X} \limsup_{n \rightarrow \infty} d(x, x_n) = \limsup_{n \rightarrow \infty} d(z, x_n) \right\}.$$

A sequence  $\{x_n\} \subset X$  is said to be  $\Delta$ -convergent to  $x_0 \in X$  if  $\text{AC}(\{x_{n_i}\}) = \{x_0\}$  for all subsequences  $\{x_{n_i}\}$  of  $\{x_n\}$ . It is denoted by  $x_n \xrightarrow{\Delta} x_0$ .

## 2.4 Resolvent of equilibrium problem

Let  $f: X \times X \rightarrow \mathbb{R}$ . In this thesis, we assume the following conditions;

- (E1)  $f(x, x) = 0$  for all  $x \in K$ ;
- (E2)  $f(x, y) + f(y, x) \leq 0$  for all  $x, y \in K$ ;
- (E3)  $f(x, \cdot): K \rightarrow \mathbb{R}$  is lower semicontinuous and convex for all  $x \in K$ ;
- (E4)  $f(\cdot, y): K \rightarrow \mathbb{R}$  is upper hemicontinuous for all  $y \in K$ .

**Theorem 2.1** (Kimura [5]). *Let  $X$  be an admissible complete CAT(1) space having the convex hull finite property and  $K \subset X$  a nonempty closed convex set. Suppose that  $f: K \times K \rightarrow \mathbb{R}$  satisfies the conditions (E1)–(E4). Define the resolvent  $R_f$  of  $f$  by*

$$R_f x = \left\{ z \in K \mid \inf_{y \in K} (f(z, y) - \log \cos d(x, y) + \log \cos d(x, z)) \geq 0 \right\}$$

for all  $x \in X$ . Then the following hold:

1.  $R_f: X \rightarrow K$  is defined as a single-valued mapping;
2.  $R_f$  satisfies the following inequality for any  $x, y \in X$ :

$$\frac{\cos d(x, R_f y)}{\cos d(x, R_f x)} + \frac{\cos d(y, R_f x)}{\cos d(y, R_f y)} \leq 2 \cos d(R_f x, R_f y);$$

3.  $F(R_f) = \text{Equil } f$  and it is closed and convex.

**Theorem 2.2** (Kimura [4]). *Let  $X$  be an admissible complete CAT(1) space having the convex hull finite property. Let  $K$  be a nonempty closed convex subset of  $X$ , and suppose that  $f: K \times K \rightarrow \mathbb{R}$  satisfies (E1)–(E4). Let  $R_f: X \rightarrow K$  be the resolvent of  $f$ . Then the inequality*

$$\lambda \frac{\cos d(v, R_{\lambda f} u)}{\cos d(v, R_{\mu f} v)} + \mu \frac{\cos d(u, R_{\mu f} v)}{\cos d(u, R_{\lambda f} u)} \leq (\lambda + \mu) \cos d(R_{\lambda f} u, R_{\mu f} v)$$

holds for all  $\lambda, \mu \in ]0, \infty[$  and  $u, v \in X$ .



## Chapter 3

# $\Delta$ -convergence theorem for Mann iteration

In this chapter, we prove a  $\Delta$ -convergence theorem for Mann type method with the resolvent of equilibrium problem. Mann type method was first studied by Mann [8] in 1953 on Hilbert spaces, and there have been many studies since then. The following theorem is a convergence theorem for Mann type method with a nonexpansive mapping on CAT(1) space.

**Theorem 3.1** (He, Fang, López, and Li [3]). *Let  $X$  be an admissible complete CAT(1) space. Suppose that  $T: X \rightarrow X$  is nonexpansive and  $F(T) \neq \emptyset$ , and let  $\{t_n\} \subset ]0, 1[$  satisfying  $\sum_{n=1}^{\infty} t_n(1 - t_n) = \infty$ .*

*Let  $\{x_n\}$  be a sequence defined by  $x_1 \in X$  with  $d(x_1, F(T)) < \pi/4$ , and*

$$x_{n+1} = t_n x_n \oplus (1 - t_n) T x_n$$

*for each  $n \in \mathbb{N}$ . Then,  $x_n \xrightarrow{\Delta} z_0 \in F(T)$ .*

The following lemma plays an important role in showing the main result.

**Lemma 3.1.** *Let  $X$  be an admissible complete CAT(1) space having the convex hull finite property. Let  $K$  be a nonempty closed convex subset of  $X$ , and suppose that  $f: K \times K \rightarrow \mathbb{R}$  satisfies (E1)–(E4). Let  $\{\lambda_n\} \subset ]0, \infty[$  and  $\{x_n\} \subset X$  be sequences satisfying  $\inf_n \lambda_n > 0$ ,  $x_n \xrightarrow{\Delta} x_0$  and  $d(x_n, R_{\lambda_n} f x_n) \rightarrow 0$ . Then,  $x_0 \in \text{Equil } f$ .*

*Proof.* Let  $\{n_i\} \subset \mathbb{N}$  be an increasing sequence and  $z \in X$ . Since

$$\begin{aligned} d(z, x_{n_i}) &\leq d(z, R_{\lambda_{n_i}} f x_{n_i}) + d(R_{\lambda_{n_i}} f x_{n_i}, x_{n_i}) \\ &\leq d(z, x_{n_i}) + 2d(R_{\lambda_{n_i}} f x_{n_i}, x_{n_i}), \end{aligned}$$

we get

$$\limsup_{i \rightarrow \infty} d(z, x_{n_i}) = \limsup_{i \rightarrow \infty} d(z, R_{\lambda_{n_i}} f x_{n_i}).$$

We first suppose that  $\sup_{n \in \mathbb{N}} \lambda_n < \infty$ . There exists  $\{\lambda_{n_j}\} \subset \{\lambda_n\}$  such that  $\lambda_{n_j} \rightarrow \lambda_0 \in [\inf_{n \in \mathbb{N}} \lambda_n, \sup_{n \in \mathbb{N}} \lambda_n]$ . Fix  $j \in \mathbb{N}$ . From theorem 2.2,

$$\lambda_{n_j} \cos d(x_0, R_{\lambda_{n_j}} f x_{n_j}) + \cos d(x_{n_j}, R_f x_0) \leq (\lambda_{n_j} + 1) \cos d(R_{\lambda_{n_j}} f x_{n_j}, R_f x_0).$$

Letting  $j \rightarrow \infty$ , we have

$$\begin{aligned} \lambda_0 \liminf_{j \rightarrow \infty} \cos d(x_0, R_{\lambda_{n_j}} f x_{n_j}) + \liminf_{j \rightarrow \infty} \cos d(x_{n_j}, R_f x_0) \\ \leq \liminf_{j \rightarrow \infty} (\lambda_{n_j} + 1) \cos d(R_{\lambda_{n_j}} f x_{n_j}, R_f x_0) \end{aligned}$$

and hence

$$\begin{aligned} \lambda_0 \cos \limsup_{j \rightarrow \infty} d(x_0, R_{\lambda_{n_j}} f x_{n_j}) + \cos \limsup_{j \rightarrow \infty} d(x_{n_j}, R_f x_0) \\ \leq (\lambda_0 + 1) \cos \limsup_{j \rightarrow \infty} d(R_{\lambda_{n_j}} f x_{n_j}, R_f x_0). \end{aligned}$$

Thus,

$$\begin{aligned} \lambda_0 \cos \limsup_{j \rightarrow \infty} d(x_0, x_{n_j}) + \cos \limsup_{j \rightarrow \infty} d(x_{n_j}, R_f x_0) \\ \leq (\lambda_0 + 1) \cos \limsup_{j \rightarrow \infty} d(x_{n_j}, R_f x_0). \end{aligned}$$

and therefore

$$\cos \limsup_{j \rightarrow \infty} d(x_0, x_{n_j}) \leq \cos \limsup_{j \rightarrow \infty} d(x_{n_j}, R_f x_0).$$

Consequently, we have

$$\limsup_{j \rightarrow \infty} d(x_0, x_{n_j}) \geq \limsup_{j \rightarrow \infty} d(x_{n_j}, R_f x_0).$$

Since  $\{x_0\} = AC(\{x_{n_j}\})$ , we have  $x_0 = R_f x_0$ . It means that  $x_0 \in \text{Equil } f$ .

We next suppose that  $\sup_{n \in \mathbb{N}} \lambda_n = \infty$ . Then, there exists  $\{\lambda_{n_j}\} \subset \{\lambda_n\}$  such that  $\lambda_{n_j} \rightarrow \infty$ . Fix  $j \in \mathbb{N}$ . Then,

$$\lambda_{n_j} \cos d(x_0, R_{\lambda_{n_j}} f x_{n_j}) + \cos d(x_{n_j}, R_f x_0) \leq (\lambda_{n_j} + 1) \cos d(R_{\lambda_{n_j}} f x_{n_j}, R_f x_0).$$

and thus

$$\cos d(x_0, R_{\lambda_{n_j}} f x_{n_j}) + \frac{\cos d(x_{n_j}, R_f x_0)}{\lambda_{n_j}} \leq \left(1 + \frac{1}{\lambda_{n_j}}\right) \cos d(R_{\lambda_{n_j}} f x_{n_j}, R_f x_0).$$

Letting  $j \rightarrow \infty$ , we get

$$\liminf_{j \rightarrow \infty} \cos d(x_0, R_{\lambda_{n_j}} f x_{n_j}) \leq \liminf_{j \rightarrow \infty} \cos d(R_f x_0, R_{\lambda_{n_j}} f x_{n_j})$$

and hence

$$\limsup_{j \rightarrow \infty} d(x_0, R_{\lambda_{n_j}} f x_{n_j}) \geq \limsup_{j \rightarrow \infty} d(R_f x_0, R_{\lambda_{n_j}} f x_{n_j}).$$

It implies that

$$\limsup_{j \rightarrow \infty} d(x_0, x_{n_j}) \geq \limsup_{j \rightarrow \infty} d(R_f x_0, x_{n_j}).$$

Since  $\{x_n\} = \text{AC}(\{x_{n_j}\})$ , we have  $x_0 = R_f x_0$ . Therefore  $x_0 \in \text{Equil } f$ .  $\square$

**Theorem 3.2.** *Let  $X$  be an admissible complete CAT(1) space having the convex hull finite property and  $K \subset X$  a nonempty closed convex set. Suppose that  $f: K \times K \rightarrow \mathbb{R}$  satisfies the conditions (E1)–(E4), and  $\text{Equil } f \neq \emptyset$ .*

*Let  $\{\lambda_n\} \subset ]0, \infty[$  and  $\{\alpha_n\} \subset [0, 1[$  be sequences satisfying  $\inf_n \lambda_n > 0$  and  $\sup_n \alpha_n < 1$ . Let  $R_{\lambda_n f}: X \rightarrow K$  be the resolvent of  $\lambda_n f$  for each  $n \in \mathbb{N}$ . Let  $\{x_n\}$  be a sequence defined by  $x_1 \in X$ , and*

$$x_{n+1} = \alpha_n x_n \oplus (1 - \alpha_n) R_{\lambda_n f} x_n$$

*for each  $n \in \mathbb{N}$ . Then,  $x_n \xrightarrow{\Delta} x_0 \in \text{Equil } f$ .*

*Proof.* Since  $\text{Equil } f \neq \emptyset$ , let  $u \in \text{Equil } f$ . From Theorem 2.1,

$$\frac{\cos d(u, R_{\lambda_n f} x_n)}{\cos d(u, R_{\lambda_n f} u)} + \frac{\cos d(x_n, R_{\lambda_n f} u)}{\cos d(x_n, R_{\lambda_n f} x_n)} \leq 2 \cos d(R_{\lambda_n f} u, R_{\lambda_n f} x_n).$$

Since  $u \in \text{Equil } f$ , we have  $d(u, R_{\lambda_n f} u) = 0$  and thus

$$\cos d(u, R_{\lambda_n f} x_n) + \frac{\cos d(x_n, u)}{\cos d(x_n, R_{\lambda_n f} x_n)} \leq 2 \cos d(u, R_{\lambda_n f} x_n).$$

It implies that  $\cos d(u, R_{\lambda_n f} x_n) \cos d(x_n, R_{\lambda_n f} x_n) \geq \cos d(x_n, u)$  and hence  $d(u, R_{\lambda_n f} x_n) \leq d(u, x_n)$ . From the parallelogram law, we get

$$\cos d(u, x_{n+1}) \geq \alpha_n \cos d(u, x_n) + (1 - \alpha_n) \cos d(u, R_{\lambda_n f} x_n) \geq \cos d(u, x_n)$$

and hence

$$d(u, x_{n+1}) \leq d(u, x_n) \leq d(u, x_1) < \frac{\pi}{2}.$$

Therefore  $\{x_n\}$  is spherically bounded and  $d(u, x_n) \rightarrow c \in [0, \frac{\pi}{2}[$ .

Further, we have

$$\begin{aligned} \cos d(u, x_{n+1}) &\geq \alpha_n \cos d(u, x_n) + (1 - \alpha_n) \cos d(u, R_{\lambda_n f} x_n) \\ &\geq \alpha_n \cos d(u, x_n) + (1 - \alpha_n) \frac{\cos d(u, x_n)}{\cos d(R_{\lambda_n f} x_n, x_n)} \end{aligned}$$

$$= \cos d(u, x_n) + (1 - \alpha_n) \cos d(u, x_n) \left( \frac{1}{\cos d(R_{\lambda_n f} x_n, x_n)} - 1 \right),$$

which implies that

$$0 \leq (1 - \alpha_n) \left( \frac{1}{\cos d(R_{\lambda_n f} x_n, x_n)} - 1 \right) \leq \frac{\cos d(u, x_{n+1})}{\cos d(u, x_n)} - 1.$$

Since  $d(u, x_n) \rightarrow c \in [0, \frac{\pi}{2}[$  and  $\sup_{n \in \mathbb{N}} \alpha_n < 1$ , we know  $d(R_{\lambda_n f} x_n, x_n) \rightarrow 0$ . Since  $\{x_n\}$  is spherically bounded, any subsequence  $\{x_{n_i}\}$  is spherically bounded. Let  $\{x_0\} = \text{AC}(\{x_n\})$  and  $\{w_0\} = \text{AC}(\{x_{n_i}\})$ . We can take a subsequence  $\{x_{n_{i_j}}\}$  such that  $x_{n_{i_j}} \xrightarrow{\Delta} z_0 \in X$ . From Lemma 3.1 and since  $d(R_{\lambda_n f} x_{n_{i_j}}, x_{n_{i_j}}) \rightarrow 0$ , we obtain  $z_0 \in \text{Equil } f$ . Further, we have

$$\begin{aligned} \limsup_{n \rightarrow \infty} d(x_n, z_0) &= \limsup_{j \rightarrow \infty} d(x_{n_{i_j}}, z_0) \\ &\leq \limsup_{j \rightarrow \infty} d(x_{n_{i_j}}, w_0) \\ &\leq \limsup_{i \rightarrow \infty} d(x_{n_i}, w_0) \\ &\leq \limsup_{i \rightarrow \infty} d(x_{n_i}, x_0) \\ &\leq \limsup_{n \rightarrow \infty} d(x_n, x_0) \leq \limsup_{n \rightarrow \infty} d(x_n, z_0). \end{aligned}$$

Therefore  $x_0 = w_0 = z_0$  and thus we get  $\{x_0\} = \text{AC}(\{x_{n_i}\})$  for all  $\{x_{n_i}\} \subset \{x_n\}$ . Consequently,  $x_n \xrightarrow{\Delta} x_0 \in \text{Equil } f$ .  $\square$

## Chapter 4

# $\Delta$ -convergence theorem for projection method

In this chapter, we prove a theorem for projection method with the resolvent of equilibrium problem.

The following is a strong convergence theorem for a nonexpansive mapping with the scheme called a shrinking projection method on Hilbert spaces.

**Theorem 4.1** (Takahashi, Takeuchi, and Kubota [10]). *Let  $H$  be a Hilbert space and  $C \subset H$  a nonempty closed convex set. Let  $T: C \rightarrow C$  be a nonexpansive mapping such that  $F(T) \neq \emptyset$ . Let  $u \in H$  and  $\{\alpha_n\} \subset [0, 1[$  be a sequence. Let  $\{x_n\}$  be a sequence and  $\{C_n\}$  subsets of  $H$  defined by  $C_1 = C$ ,  $x_1 \in C$  and*

$$\begin{aligned}y_n &= \alpha_n x_n + (1 - \alpha_n)Tx_n, \\C_{n+1} &= \{z \in C \mid \|y_n - z\| \leq \|x_n - z\|\} \cap C_n, \\x_{n+1} &= P_{C_{n+1}}u.\end{aligned}$$

Then,  $x_n \rightarrow P_{F(T)}u \in C$ .

Further in 2023, Kimura proved the  $\Delta$ -convergence theorem by modified shrinking projection method for a nonexpansive mapping in a  $\text{CAT}(0)$  space.

**Theorem 4.2** ([6]). *Let  $X$  be a Hadamard space and suppose that a subset  $\{z \in X \mid d(x, y) \leq d(y, z)\}$  is convex for  $x, y \in X$ . Suppose that  $T: X \rightarrow X$  be a nonexpansive mapping and  $F(T) \neq \emptyset$ . Let  $\{x_n\}$  be a sequence and  $\{C_n\}$  be a convex subsets of  $X$  defined by  $x_1 \in X$ ,  $C_1 = X$ , and*

$$\begin{aligned}C_{n+1} &= \{z \in X \mid d(Tx_n, z) \leq d(x_n, z)\} \cap C_n, \\x_{n+1} &= P_{C_{n+1}}x_n\end{aligned}$$

for each  $n \in \mathbb{N}$ . Then,  $x_n$  is well-defined and  $x_n \xrightarrow{\Delta} x_0 \in F(T)$ .

We consider the projection method for a resolvent of equilibrium problem in  $\text{CAT}(1)$  space, and show the following  $\Delta$ -convergence theorem.

**Theorem 4.3.** *Let  $X$  be an admissible complete CAT(1) space having the convex hull finite property and  $C \subset X$  a nonempty closed convex set. Suppose that  $f: C \times C \rightarrow \mathbb{R}$  satisfies the conditions (E1)–(E4), and  $\text{Equil } f \neq \emptyset$ . Let  $\{\lambda_n\} \subset ]0, \infty[$  be a sequence satisfying  $\inf_n \lambda_n > 0$ . Suppose that  $\{z \in X \mid d(x, z) \leq d(y, z)\}$  is convex for all  $x, y \in X$ . Let  $R_{\lambda_n f}: X \rightarrow C$  be the resolvent of  $\lambda_n f$  for each  $n \in \mathbb{N}$ . Let  $\{x_n\}$  be a sequence and  $C_n$  a convex subset of  $X$  defined by  $x_1 \in C$ ,  $C_1 = C$ , and*

$$\begin{aligned} C_{n+1} &= \{z \in C \mid d(R_{\lambda_n f} x_n, z) \leq d(x_n, z)\} \cap C_n, \\ x_{n+1} &= P_{C_{n+1}} x_n \end{aligned}$$

for each  $n \in \mathbb{N}$ . Then,  $\{x_n\}$  is well-defined and  $x_n \xrightarrow{\Delta} x_0 \in \text{Equil } f$ .

*Proof.* We first show by induction that  $F(R_{\lambda_n f} x) \subset C_n$  and  $x_n$  is well-defined for all  $n \in \mathbb{N}$ .  $F(R_{\lambda_1 f}) \subset C_1$  is obvious. Suppose  $F(R_{\lambda_k f}) \subset C_k$ . Let  $x \in C$  and  $z \in F(R_{\lambda_k f})$ . Then

$$\frac{\cos d(x, R_{\lambda_k f} z)}{\cos d(x, R_{\lambda_k f} x)} + \frac{\cos d(z, R_{\lambda_k f} x)}{\cos d(z, R_{\lambda_k f} z)} \leq 2 \cos d(R_{\lambda_k f} x, R_{\lambda_k f} z).$$

Since  $z \in F(R_{\lambda_k f})$ , we have  $\cos d(R_{\lambda_k f} x, z) \cos d(x, R_{\lambda_k f} x) \geq \cos d(x, z)$  and thus  $d(x, R_{\lambda_k f} x) \leq d(x, z)$ . This implies that  $z \in C_{k+1}$  and hence  $F(R_{\lambda_{k+1} f}) \subset C_{k+1} \neq \emptyset$ . Therefore  $F(R_{\lambda_n f}) \subset C_n \neq \emptyset$  for all  $n \in \mathbb{N}$ . Further, we know that  $C_n$  is closed and convex for all  $n \in \mathbb{N}$  and thus  $\{x_n\}$  is well-defined.

Next, we show that  $x_n \xrightarrow{\Delta} x_0 \in \text{Equil } f$ . Let  $u \in F(R_{\lambda_n f})$ . Since  $\{P_{C_n}\}$  is quasi-nonexpansive,  $d(x_{n+1}, u) = d(P_{C_{n+1}} x_n, u) \leq d(x_n, u)$  and thus  $\{d(x_n, u)\}$  converges to some  $c \in [0, \pi/2]$ . From the definition of CAT(1) space, we have

$$\begin{aligned} &\cos d(x_{n+1}, x_n) \sin d(u, x_{n+1}) \\ &= \cos d(P_{C_{n+1}} x_n, x_n) \sin d(u, P_{C_{n+1}} x_n) \\ &\geq \cos d(tu \oplus (1-t)P_{C_{n+1}} x_n, x_n) \sin d(u, P_{C_{n+1}} x_n) \\ &\geq \cos d(u, x_n) \sin td(u, P_{C_{n+1}} x_n) + \cos d(P_{C_{n+1}} x_n, x_n) \sin(1-t)d(u, P_{C_{n+1}} x_n) \\ &= \cos d(u, x_n) \sin td(u, x_{n+1}) + \cos d(x_{n+1}, x_n) \sin(1-t)d(u, x_{n+1}) \end{aligned}$$

and hence

$$(\sin d(u, x_{n+1}) - \sin(1-t)d(u, x_{n+1})) \cos d(x_{n+1}, x_n) \geq \cos d(u, x_{n+1}) \sin td(u, x_{n+1}).$$

Using sum to product formulas, we have

$$\begin{aligned} &(\sin d(u, x_{n+1}) - \sin(1-t)d(u, x_{n+1})) \cos d(x_{n+1}, x_n) \\ &= 2 \cos \frac{(2-t)d(u, x_{n+1})}{2} \sin \frac{td(u, x_{n+1})}{2} \cos \frac{t}{2} d(x_n, x_{n+1}). \end{aligned}$$

From half angle formulas, we get

$$\begin{aligned} & 2 \cos \frac{(2-t)d(u, x_{n+1})}{2} \sin \frac{td(u, x_{n+1})}{2} \cos d(x_n, x_{n+1}) \\ & \geq \cos d(u, x_n) \sin d(u, x_{n+1}) \\ & = \cos d(u, x_n) 2 \sin \frac{t}{2} d(u, x_{n+1}) \cos \frac{t}{2} d(u, x_{n+1}). \end{aligned}$$

This implies that

$$\cos \frac{(2-t)d(u, x_{n+1})}{2} \cos d(x_n, x_{n+1}) \geq \cos d(u, x_n) \cos \frac{t}{2} d(u, x_{n+1}),$$

and letting  $t \rightarrow 0$ , we get

$$\cos d(u, x_{n+1}) \cos d(x_n, x_{n+1}) \geq \cos d(u, x_n).$$

Since  $d(x_n, u) \rightarrow c$ , we have

$$1 \geq \cos d(x_{n+1}, x_n) \geq \frac{\cos d(u, x_n)}{\cos d(u, x_{n+1})} \rightarrow \frac{\cos c}{\cos c} = 1$$

as  $n \rightarrow \infty$ , and thus  $d(x_{n+1}, x_n) \rightarrow 0$ . Since  $x_{n+1} \in C_{n+1}$  and  $d(x_{n+1}, x_n) \rightarrow 0$ , we have

$$\begin{aligned} 0 \leq d(R_{\lambda_n} f x_n, x_n) & \leq d(R_{\lambda_n} f x_n, x_{n+1}) + d(x_{n+1}, x_n) \\ & \leq d(x_n, x_{n+1}) + d(x_{n+1}, x_n) \rightarrow 0 \end{aligned}$$

and hence

$$d(R_{\lambda_n} f x_n, x_n) \rightarrow 0.$$

Since  $\{x_n\}$  is spherically bounded, every subsequence  $\{x_{n_i}\}$  of  $\{x_n\}$  is also spherically bounded. Let  $\{x_0\} = \text{AC}(\{x_n\})$  and  $\{w_0\} = \text{AC}(\{x_{n_i}\})$ . We can take a subsequence  $\{x_{n_{i_j}}\} \subset \{x_{n_i}\}$  such that  $\Delta$ -convergence to some  $z_0 \in C$ . Since  $d(R_{\lambda_n} f x_n, x_n) \rightarrow 0$ , by Lemma 3.1 we get  $z_0 \in \text{Equil } f$ . From the definition of the asymptotic center, we get

$$\begin{aligned} \limsup_{n \rightarrow \infty} d(x_n, z_0) & = \limsup_{j \rightarrow \infty} d(x_{n_{i_j}}, z_0) \\ & \leq \limsup_{j \rightarrow \infty} d(x_{n_{i_j}}, w_0) \\ & \leq \limsup_{i \rightarrow \infty} d(x_{n_i}, w_0) \\ & \leq \limsup_{i \rightarrow \infty} d(x_{n_i}, x_0) \\ & \leq \limsup_{n \rightarrow \infty} d(x_n, x_0) \leq \limsup_{n \rightarrow \infty} d(x_n, z_0). \end{aligned}$$

Therefore  $x_0 = w_0 = z_0$  and thus we get  $\{x_0\} = \text{AC}(\{x_{n_i}\})$  for all  $\{x_{n_i}\} \subset \{x_n\}$ . Consequently,  $x_n \xrightarrow{\Delta} x_0 \in \text{Equil } f$ .  $\square$

Further, we show that a projection onto subset of CAT(1) space strong convergence to the same point as sequence for metric projection.

**Theorem 4.4.** *Let  $X$  be an admissible complete CAT(1) space having the convex hull finite property and  $C \subset X$  a nonempty closed convex set. Suppose that  $f: C \times C \rightarrow \mathbb{R}$  satisfies the conditions (E1)–(E4), and  $\text{Equil } f \neq \emptyset$ . Let  $\{\lambda_n\} \subset ]0, \infty[$  be a sequence satisfying  $\inf_n \lambda_n > 0$ . Suppose that  $\{z \in X \mid d(x, z) \leq d(y, z)\}$  is convex for all  $x, y \in C$ . Let  $R_{\lambda_n f}: X \rightarrow C$  be the resolvent of  $\lambda_n f$  for each  $n \in \mathbb{N}$ . Let  $\{x_n\}$  be a sequence and  $C_n$  be a convex subset of  $X$  defined by  $x_1 \in C$ ,  $C_1 = C$ , and*

$$\begin{aligned} C_{n+1} &= \{z \in C \mid d(R_{\lambda_n f} x_n, z) \leq d(x_n, z)\} \cap C_n, \\ x_{n+1} &= P_{C_{n+1}} x_n \end{aligned}$$

for each  $n \in \mathbb{N}$ . Let  $D \subset X$  be closed and convex such that  $\text{Equil } f \subset D \subset \bigcap_{n=1}^{\infty} C_n$ . Then,  $P_D x_n \rightarrow x_0$ , where  $x_0$  is the  $\Delta$ -limit of  $\{x_n\}$ .

*Proof.* By theorem 4.3, we have that  $x_n \xrightarrow{\Delta} x_0 \in \text{Equil } f$ . Using this fact, we show  $P_D x_n \rightarrow x_0$ . Since

$$d(P_D x_{n+1}, x_{n+1}) \leq d(P_D x_n, x_{n+1}) = d(P_D x_n, P_{C_{n+1}} x_n) \leq d(P_D x_n, x_n),$$

$\{\cos d(P_D x_n, x_n)\}$  is a Cauchy sequence. Hence, there exists  $\{\alpha_n\} \subset \mathbb{R}$  such that  $\alpha_n \rightarrow 0$  and  $\cos d(P_D x_m, x_m) - \cos d(P_D x_n, x_n) \leq \alpha_n$  if  $m \geq n$ . We have

$$\frac{\alpha_n}{\cos d(P_D x_m, x_m)} \geq \frac{\cos d(P_D x_m, x_m)}{\cos d(P_D x_m, x_m)} - \frac{\cos d(P_D x_n, x_n)}{\cos d(P_D x_m, x_m)},$$

and thus

$$\frac{\cos d(P_D x_n, x_n)}{\cos d(P_D x_m, x_m)} \geq 1 - \frac{\alpha_n}{\cos d(P_D x_m, x_m)} \geq 1 - \frac{\alpha_n}{\cos d(P_D x_1, x_1)}.$$

Further, since  $\cos d(P_D x_m, x_m) \cos d(P_D x_m, P_D x_n) \geq \cos d(P_D x_n, x_m)$ , we have

$$\begin{aligned} \cos d(P_D x_m, P_D x_n) &\geq \frac{\cos d(P_D x_n, x_m)}{\cos d(P_D x_m, x_m)} \\ &\geq \frac{\cos d(P_D x_n, x_n)}{\cos d(P_D x_m, x_m)} \geq 1 - \frac{\alpha_n}{\cos d(P_D x_1, x_1)}. \end{aligned}$$

Hence,  $\{P_D x_n\}$  is a Cauchy sequence and we get  $\{P_D x_n\}$  converges to some  $y_0 \in C$ . Since  $x_n \xrightarrow{\Delta} x_0 \in \text{Equil } f$ , we have

$$\begin{aligned} \limsup_{n \rightarrow \infty} d(y_0, x_n) &\leq \limsup_{n \rightarrow \infty} (d(y_0, P_D x_n) + d(P_D x_n, x_n)) \\ &= \limsup_{n \rightarrow \infty} d(P_D x_n, x_n) \leq \limsup_{n \rightarrow \infty} d(x_0, x_n). \end{aligned}$$

Therefore,  $y_0 = x_0$  and we get  $P_D x_n \rightarrow x_0 \in \text{Equil } f$ . □



# Chapter 5

## Conclusion

In this thesis, we considered an equilibrium problem defined on an admissible complete CAT(1) space and obtain two different types of approximation theorems by using the resolvent operator for an equilibrium problem.

The first result is a Mann type  $\Delta$ -convergence theorem as follows;

**Theorem 3.3.** *Let  $X$  be an admissible complete CAT(1) space having the convex hull finite property and  $K \subset X$  a nonempty closed convex set. Suppose that  $f: K \times K \rightarrow \mathbb{R}$  satisfies the conditions (E1)–(E4), and  $\text{Equil } f \neq \emptyset$ .*

*Let  $\{\lambda_n\} \subset ]0, \infty[$  and  $\{\alpha_n\} \subset [0, 1[$  be sequences satisfying  $\inf_n \lambda_n > 0$  and  $\sup_n \alpha_n < 1$ . Let  $R_{\lambda_n f}: X \rightarrow K$  be the resolvent of  $\lambda_n f$  for each  $n \in \mathbb{N}$ . Let  $\{x_n\}$  be a sequence defined by  $x_1 \in X$ , and*

$$x_{n+1} = \alpha_n x_n \oplus (1 - \alpha_n) R_{\lambda_n f} x_n$$

*for each  $n \in \mathbb{N}$ . Then,  $x_n \xrightarrow{\Delta} x_0 \in \text{Equil } f$ .*

In the second result, we used a modified shrinking projection method, which was recently proposed by Kimura, and obtain an iterative sequence which is  $\Delta$ -convergent to the solution to an equilibrium problem.

**Theorem 4.3.** *Let  $X$  be an admissible complete CAT(1) space having the convex hull finite property and  $C \subset X$  a nonempty closed convex set. Suppose that  $f: C \times C \rightarrow \mathbb{R}$  satisfies the conditions (E1)–(E4), and  $\text{Equil } f \neq \emptyset$ . Let  $\{\lambda_n\} \subset ]0, \infty[$  be a sequence satisfying  $\inf_n \lambda_n > 0$ . Suppose that  $\{z \in X \mid d(x, z) \leq d(y, z)\}$  is convex for all  $x, y \in X$ . Let  $R_{\lambda_n f}: X \rightarrow C$  be the resolvent of  $\lambda_n f$  for each  $n \in \mathbb{N}$ . Let  $\{x_n\}$  be a sequence and  $C_n$  a convex subset of  $X$  defined by  $x_1 \in C$ ,  $C_1 = C$ , and*

$$\begin{aligned} C_{n+1} &= \{z \in C \mid d(R_{\lambda_n f} x_n, z) \leq d(x_n, z)\} \cap C_n, \\ x_{n+1} &= P_{C_{n+1}} x_n \end{aligned}$$

*for each  $n \in \mathbb{N}$ . Then,  $\{x_n\}$  is well-defined and  $x_n \xrightarrow{\Delta} x_0 \in \text{Equil } f$ .*

Further, in this scheme, we found a strongly convergent sequence to the same point as the original iterative sequence by using metric projections onto a subset having an

appropriate property.

**Theorem 4.4.** *Let  $X$  be an admissible complete CAT(1) space having the convex hull finite property and  $C \subset X$  a nonempty closed convex set. Suppose that  $f: C \times C \rightarrow \mathbb{R}$  satisfies the conditions (E1)–(E4), and  $\text{Equil } f \neq \emptyset$ . Let  $\{\lambda_n\} \subset ]0, \infty[$  be a sequence satisfying  $\inf_n \lambda_n > 0$ . Suppose that  $\{z \in X \mid d(x, z) \leq d(y, z)\}$  is convex for all  $x, y \in C$ . Let  $R_{\lambda_n f}: X \rightarrow C$  be the resolvent of  $\lambda_n f$  for each  $n \in \mathbb{N}$ . Let  $\{x_n\}$  be a sequence and  $C_n$  be a convex subset of  $X$  defined by  $x_1 \in C$ ,  $C_1 = C$ , and*

$$\begin{aligned} C_{n+1} &= \{z \in C \mid d(R_{\lambda_n f} x_n, z) \leq d(x_n, z)\} \cap C_n, \\ x_{n+1} &= P_{C_{n+1}} x_n \end{aligned}$$

for each  $n \in \mathbb{N}$ . Let  $D \subset X$  be closed and convex such that  $\text{Equil } f \subset D \subset \bigcap_{n=1}^{\infty} C_n$ . Then,  $P_D x_n \rightarrow x_0$ , where  $x_0$  is the  $\Delta$ -limit of  $\{x_n\}$ .

# Acknowledgments

I would like to express to Professor Yasunori Kimura for his careful guidance when I was at a loss in the course of this research. I'd like to use this opportunity to thank Professor Kimura.

# Bibliography

- [1] E. Blum and W. Oettli, *From optimization and variational inequalities to equilibrium problems*, Math. Student. **63** (1994), 123–145.
- [2] P. L. Combettes and S. A. Hirstoaga, *Equilibrium programming in Hilbert spaces*, J. Nonlinear Convex Anal. **6** (2005), 117–136.
- [3] J. S. He, D. H. Fang, G. López and C. Li, *Mann’s algorithm for nonexpansive mappings in  $CAT(\kappa)$  spaces*, Nonlinear Anal. **75** (2012), 445–452.
- [4] Y. Kimura, *Note on the resolvent for equilibrium problems in a complete geodesic space*, preprint.
- [5] Y. Kimura, *Resolvents of equilibrium problems on a complete geodesic space with curvature bounded above*, Carpathian J. Math. **37** (2021), 463–476.
- [6] Y. Kimura, *Comparison of convergence theorems for a complete geodesic space*, RIMS kôkyûroku, no. **2240** (2023).
- [7] Y. Kimura and T. Oguchi, *An approximation theorem to a solution to an equilibrium problem in complete  $CAT(1)$  space*, Study on nonlinear analysis and convex analysis, RIMS Kôkyûroku, vol. 2240, Kyoto University, Kyoto, 2023, 97–103.
- [8] W. R. Mann, *Mann value methods in iteration*, Proc. Amer. Soc **4** (1953), 506–510.
- [9] S. Reich, *Weak convergence theorems for nonexpansive mappings in Banach spaces*, J. Math. Anal. Appl. **67** (1979), 274–276.
- [10] W. Takahashi, Y. Takeuchi and R. Kubota, *Strong convergence theorems by hybrid methods for families of nonexpansive mappings in Hilbert spaces*, J. Math. Anal. Appl. **341** (2008), 276–286.